

**ROBOTICS
KEYS**

I Choose the correct alternative:

1. a
2. d
3. c
4. b
5. a
6. c
7. b
8. b
9. d
10. d

II Fill in the blanks

11. Slew motion
12. Lagrange –Euler
13. Joint space
14. Joint interpolated
15. Hydraulic
16. Wrist force torque
17. Actuators
18. Trajectory
19. Processing Applications
20. $n = A/360^\circ$